

Quadraticproblem assignment



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Quadratic assignment problem is one of the most known and challenging combinatorial optimization problems. In this study, a new tabu search algorithm is proposed to solve the quadratic assignment problem. The performance of the proposed approach is tested on with 25, 50 and 100-department instances which are taken from QAPLib.

Quadratic assignment problem (QAP) is introduced by Koopmans and Beckman in 1957. It can be described as follows: given $n \times n$ matrices $A = (a_{ij})$ and $B = (b_{ij})$ where matrices represent flow and distance, respectively. Find a permutation π minimizing $n \times n \min_{\pi \in Q} f(\pi) = \sum_{i=1}^n \sum_{j=1}^n a_{ij} b_{\pi(i)\pi(j)}$ where Q is the set of permutations of n elements [1]. Shani and Gonzalez have shown that QAP is NP-hard [8]. Solving this problem optimality for the large instances is computationally infeasible.

Therefore, heuristic approaches have to be used for solving medium- and large-scale QAPs. In this study, tabu search (TS) algorithm is used to solve QAP. Tabu search technique was developed by Glover [2, 3]. This method has become very popular and is widely used for a variety of problems [4]. Tabu search is based on the neighborhood search with local-optima avoidance but in a rather deterministic way. The key idea of tabu search is allowing climbing moves when no improving neighboring solution exists. However, some moves are to be forbidden at a present search iteration in order to avoid cycling.

The proposed tabu search algorithm is tested with different neighborhood sizes, tabu tenors and termination conditions. During the tests 25-department [7] and 50, 100-department [9] instances are used which are taken from

QAPLib. This paper will proceed as follows. In section 2, mathematical model of the QAP is given. In section 3, proposed SA is presented. Finally in section 4 computational results are given.

2 Problem Formulation

In this study, QAP with n departments and n locations with minimizing costs between placed departments is considered. The cost is obtained by product of flows and distances between departments.

Integer linear model of the problem is as follows. Set N : Department (or location) set where $N = \{1, 2, \dots, n\}$ Indices i, k : The department index used as unique identifier for each department. j, l : The location index used as unique identifier for each location. Parameters n : Number of departments (or locations) a_{ik} : Total flow department i to department k . b_{jl} : Distance location j to department l .

Decision Variables

1 If department i assigned to location j $x_{ij} = 1$ otherwise $x_{ij} = 0$

2 Model

$$\min \sum_{i=1}^n \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n a_{ik} b_{jl} x_{ij} x_{kl} \quad (1)$$

s. t. $\sum_{j=1}^n x_{ij} = 1 \quad \forall i=1, \dots, n$ (2)

$$\sum_{i=1}^n x_{ij} = 1 \quad \forall j=1, \dots, n$$
 (3)
$$x_{ij} \in \{0, 1\} \quad \forall i, j$$
 (4)

Equation (1) is the objective function that minimizes the costs. Equation (2) ensures that each department is assigned exactly one location. Similarly, equation (3) ensures that each location is assigned to exactly one department. Equation (4) is the binary integrality constraints.

3 Tabu Search

Tabu search starts from an initial solution s where $s \in S$, S is the set of solution of combinatorial optimization problem. At each step of the procedure, a set $N(s)$ of the neighboring solutions of the current solution s is considered and the move that improves most the objective function value is chosen.

If there are no improving moves, tabu search chooses one that least degrades the objective function. In order to avoid the returning to the local

optimal solution just visited, the reverse move must be prohibited. This is done by storing this move in a memory (or more precisely short-time-memory) managed like a circular list and called a tabu list. In that way, the tabu list keeps information on the last moves which have been done during the search process. However, it might be worth returning after a while to a solution visited previously to search in another direction.

Consequently, an aspiration criterion is introduced to permit the tabu status to be dropped under certain favorable circumstances [6]. In the following subsections elements of the proposed tabu search algorithm is explained.

Departments Locations 1 3 2 5 3 1 4 8 5 6 6 2 7 4 8 7 Table 1: Example

solution representation Figure 1: Illustrative example for the solution

representation 3. 1 Solution Representation In this study, solution is represented as permutation of locations (π). Each solution represents assignment of i th department to $\pi(i)$ th locations where $i = \{1, 2, \dots, n\}$.

Sample representation is shown in the Table 1.

In Table 1, there are $n = 8$ departments (and locations), and the example solution represents $1 \rightarrow 3, 2 \rightarrow 5, \dots, 8 \rightarrow 7$ department-location assignments.

The department-location assignment is also illustrated in Fig. 1. 3. 2 Cost Function The equation (5) is the cost function of the explained solution (π)

representation. The goal of the algorithm is to find a solution which minimizes this value.
$$f(\pi) = \sum_{i=1}^n \sum_{j=1}^n a_{ij} b_{\pi(i)\pi(j)} \quad (5)$$

3. 3 Neighborhood Structure In this study, a standard swap operation is used as a neighborhood structure. Basically, location of two different department is exchanged.

In this neighborhood structure (Neighborhood-1), all possible swaps are evaluated. So that complexity of the neighborhood structure is $O(n^2)$. The algorithm of the neighborhood structure is given in Algorithm 1.

4 Input: Solution $s \in S$ Output: Neighbors of s for $i \in \{1, \dots, n\}$

4 Tabu List In the propped tabu search algorithm, moves are stored in the tabu list. For example, if the locations i and j are swapped, then $\text{swap}(i, j)$ is added to tabu list. This tabu also restricts the $\text{swap}(j, i)$ move. Another point about the tabu search is tabu list size. Two different tabu lists are tested which are fixed-sized and dynamic-sized.

In the fixed-sized

No	1	2	3	4	5	6	Neighbors	2	1	3	4	3	2	1	4	4	2	3	1	1	3	2	4	1
4	3	2	1	2	4	3	No	1	2	3	Neighbors	2	1	3	4	1	3	2	4	1	2	4	3	

Table 2: Comparison of neighbors for Neighborhood-1 and Neighborhood-2 tabu list, size of the

tabu list remains same until the termination condition occurs. In the dynamic-sized tabu list, tabu list size is decreased by using equation (6). In this function T_0 represents the initial tabu list size, T_N represents final tabu list size and n_{iter} represents the number of iterations. This idea is similar to the cooling schedule for the simulated annealing.

$$T_i = (T_0 - T_N) \cdot \frac{1}{1 + \cos\left(\frac{2\pi n_{iter}}{n_{iter}}\right)} + T_N \quad (6)$$

One of the most advantage side of the tabu search is memory usage. In this study, frequency based tabu list is implemented to use the benefit of long term memory. Previously visited moves are penalized to diversify the proposed tabu search. For this purpose, frequency of each visited move is stored and each move is penalized with equation (7). In this equation Z_p represents penalized objective value, $Z_{i,j}$ represents the objective value of when $\text{swap}(i, j)$ is applied, $f_{i,j}$ represents the frequency of

swap(i, j) and n_{iter} represents the number of iterations. $Z_p = Z_{i, j} + Z_{i, j} f_{i, j}$
 $n_{iter} (7) 3. 5$

Aspiration Criterion In the proposed tabu search an aspiration criterion is used. The tabu status of an attribute can be revoked if that would allow the search to reach a solution of smaller cost than the best known solution having the given attribute.

3. 6 Termination Criterion In tabu search procedure, two different stopping criteria is used which are as follows.

- Maximum number of iterations (n_{iter}).
- If the best-known solution is not improved consecutive “ n_{imp} ” iterations.

4 Computational Results Proposed tabu search algorithm is tested on 25, 50 and 100 departments test instances which are taken from QAPLib.

Proposed algorithm is coded in C++ and all tests are conducted in Linux machine with 32GB ram. As the tabu search is a deterministic search technique, if the input solution and the other parameters of the tabu search remain same there will be no difference on the obtained solution between different replicas. So that, only one replica is taken for each test case, and best obtained solution for the replica is reported. The test cases are as follows:

- Initial solution is changed 5 times.
- Different tabu list sizes (t_{size}) are tested. $t_{size} = \{6, 8, 10\}$
- Dynamic tabu list size is tested. Tabu list size is defined by using Equation (6).
- Effect of aspiration criterion (with and without aspiration criterion).
- Number of evaluated neighbors n_2 and n_1
- Effect of long-term memory (with and without frequency based tabu list).

These cases are tested by changing each of them one by one. So that, initial parameter setting should be defined. The initial parameters are as follows;

- Initial solution is taken same for all tests.
- Fixed-sized tabu list and t_{size}

= 8. • No aspiration criterion. • No long-term memory. • Neighborhood-1 is used, so that number of evaluated neighbors is $n \cdot 2$. • Maximum number of iteration is used for the stopping criterion, and $n_{iter} = 250$.

Nug25 test instance is solved with these initial parameters, and 3762 is obtained. During the evaluation process current solution and best-known solution are logged, and by using these logs two figures are plotted in Fig. 2. As seen from Fig. 2b, best solution is improved when the search procedure is close to termination. So that, best-known solution may be improved if the n_{iter} is increased. A new replica is taken with $n_{iter} = 300$, but no change is observed on the best-obtained solution. Effect of Initial solution Five different initial solution is evaluated, and following results are obtained 3748, 3768, 3772, 3744, 3788.

The average of the solutions is 3764 and the range of the solutions is 44. Relative difference gives more meaningful results. Relative range is obtained by dividing the range of the solutions to the of the average value, and this value is 0.012. These results show that the performance of algorithm is not highly affected with the input solution. On the other hand, we cannot say initial solution has no effect on the performance of the tabu search. Because, one of obtained solution is 3744 that is an optimal solution, another obtained solution is 3788 that is a little bit far from optimal solution. Effect of tabu list size Two more different tabu list sizes are evaluated which are 6 and 10, and the initial tabu list size is not changing during the evaluation. When the tabu list size is 8 the best objective value was obtained as 3762. Tabu list size is decrease to 6, and the best obtained solution's objective value is 3774. As an another test case, tabu list size is increased to 10, and the best obtained

solution's objective value is 3762. From the obtained results, it is possible to say that increasing the tabu list size improves the performance of tabu search. (a) Change of the current solution with respect to iteration b) Change of the best obtained solution with respect to iteration Figure 2: Obtained solutions with respect to iterations 9 search. This situation occurs, because tabu list size is one of the diversification operators of the tabu search. So, when we increase the tabu list size, we prevent tabu search from the early convergence. On the other, increasing size of the tabu search too much concludes with the bad result, because most of the possible moves may be restricted with the long lengthed tabu list. Effect of dynamic tabu list As well as fixed-length tabu list, dynamic-length tabu list is tested too.

Details of the dynamic tabu list is explained before. To determine the size of the tabu list in each iteration equation (6) is used. In this function, T_0 is set to 10 and T_N is set to 5. Non-integer results may be obtained by using equation (6), so that obtained function result is rounded to closest integer number to determine current iteration's tabu list size. During the evaluation the result of the equation (6) (Fig. 3a) and current tabu list size (Fig. 3b) is logged, and the corresponding figures are given in Fig. 3. When the dynamic-length tabu list is used the best obtained solution's objective value is 3770.

The solution is worse than previously obtained solutions. Probably, decreasing the size of the tabu list depending on iteration cause premature convergence. It is better to use fixed-length tabu list instead of dynamic-length tabu list. Effect of aspiration criterion In this test case effect of aspiration criterion is tested. Proposed tabu search is tested with initial test

cases including aspiration criterion, and the best obtained solution is 3748. Considerable difference is obtained with aspiration criterion compared to initial parameter solution.

In this replica best-obtained solution is improved 5-times by using aspiration criterion. This considerable performance increase is obvious, because with aspiration criterion it is allowed to increase the best-obtained solution even if this move is a tabu effect of neighborhood. Instead of whole neighbourhood (Neighborhood-1), the performance of subset of this neighborhood (Neighborhood-2) is tested. Effect of long-term memory. Aspiration criterion and effect of long term memory is tested together. 10 (a) Value of the equation (6) with respect to iterations (b) Current tabu list size with respect to iterations

Figure 3: Dynamic tabu list size logs with respect to iterations 11 References

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