

# Is tribology approaching its golden age? grand challenges in engineering educatio...

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## Invisible Tribology

Whether a technical device or a living being—every system is made up of connected parts. These connections of various kinds—from simple supports to rivets, screws, glued connections, various types of bearings, wheels, and so on are the subject of a science named *Tribology*. Tribology is a subject integral to any mechanical system containing moving parts or joints—starting with molecular “machines” (as motor proteins in living cells) ( [Dudko et al., 2003](#) ) and micro and nano mechanical systems ( [Bhushan et al., 1995](#) ) over the huge field of traditional macroscopic tribology ( [Dowson, 1979](#) ) up to the contacts between tectonic plates ( [Scholz, 2002](#) ). The word “Tribology” was introduced 1966 by the British commission guided by Jost ( [1966](#) ). The Jost Report identified incorrect lubrication and the accompanying wear and friction issues as the main reasons for the failure of mechanical systems. Since then it has been (somewhat) widely recognized that tribology has immediate influence on global energy consumption, costs and emissions—key technological and hot political issues of the modern society ( [Holmberg and Erdemir, 2017](#) ). And yet, if you ask people on the street what “Tribology” is, most of them will not be able to associate this word with any practical object or problem. How can the tremendous importance of tribology be reconciled with its relatively low social and technological visibility?

## What Is the Reason for Low Visibility of Tribology?

The answer may lie in the poor *availability* of tribology to the broader engineering community. Scientific and technological visibility and public perception of each discipline is determined not only by its importance but

very decisively also by its availability. Thus, Analysis was almost a sacral science only for a few “initiates” until Leibnitz invented his intuitive and practical notations ( [Leibnitz, 1674-1676](#) ). This seemingly “merely didactical” invention made Analysis available literally for everybody—now it is a part of the curriculum of any high school. The availability of a subject is strongly associated with its complexity, and the complexity of the mechanics and physics of interfaces is notoriously high. Just a superficial glance in an anatomic atlas ( [Bourgerly, 2017](#) ) shows that the main elements of the supporting structure of the human body, bones, are—in spite of their complicated internal structure—much simpler than the joints. The latter have a truly spectacular architecture and very specialized material properties, which still cannot be reproduced artificially ( [Jin and Dowson, 2013](#) ). No wonder that it is much more difficult to repair the joints than it is to mend bones. Structural elements and their joints are both omnipresent in a variety of systems—they are both generic, unavoidable aspects of any structure. The difference between them is in the availability of models used to describe them: For the basics of mechanics of materials students only need proficiency in analysis of one variable and the simplest ordinary differential equations, while the simplest (Hertzian) contact problem is formulated as an integral equation with mixed boundary conditions. This qualitative difference in complexity is the reason for the fact that students of almost all engineering majors study the theory of beams in their first or second semester, but only acquire a very rudimentary notion of the mechanics of connections.

## **Did Two Centuries Since the Work of Coulomb Bring Progress?**

Tribology is the science of friction, wear and lubrication. The first experimental study of friction that was broadly publicly discussed and had a decisive impact on the subsequent development of science and engineering seems to be the memoir of Amontons ( [1699](#) ). He was the first to formulate, based on experimental observations, the “ law of friction” which is now widely known as “ Amontons' law.” In 1781 Charles Augustin de Coulomb published his remarkable, timeless book on friction (see available later edition, [Coulomb, 1821](#) ) where he described many properties of dry friction that even today remain subjects of active research. In particular, he investigated the dependency of the coefficient of friction on time, velocity, normal force, apparent contact area, humidity and material pairing. Some of his observations—e. g., the explicit time dependency of the coefficient of friction—have been understood only two hundred years later ( [Rice and Ruina, 1983](#) ; [Dieterich and Kilgore, 1994](#) ) and many remain not understood to this day. For example, Coulomb found that the intensity of friction in the contact of wood on metal, depending on the duration of contact, slowly increases and reaches its peak after 4–5 days, and sometimes more. In contact of two metals, friction shows completely different behavior: it achieves the stationary value in an instant. In wood on wood contact friction achieves the stationary value in a few minutes ( [Popova and Popov, 2015](#) ). These observations are more than 200 years old, but only began to be understood on the micro scale very recently ( [Carpick and Bennewitz, 2014](#) ).

The most striking deficiency in the current state of the art of tribology, is that we still cannot *predict* the coefficient of friction in practically any pairing, and in many cases we even do not really understand what the main governing parameters are. This is due to the complexity of physical processes determining tribological properties ( [Persson and Tosatti, 1996](#) ): contact interactions, adsorbed layers ( [Robbins and Krim, 1998](#) ; [He et al., 1999](#) ; [Müser et al., 2001](#) ), tribochemical reactions, mixing processes and wear ( [Scherge et al., 2003](#) ), elastohydrodynamic lubrication ( [Ertel, 1939](#) ; [Hamrock and Dowson, 1977](#) ), boundary lubrication ( [Kenausis et al., 2000](#) ), shear melting ( [Persson and Popov, 2000](#) ), cavitation ( [Etsion, 2013](#) ; [Savio et al., 2016](#) ), adhesion ( [Rabinowicz, 1961](#) ), interaction with system dynamics ( [Kado et al., 2014](#) ; [Teidelt, 2015](#) ; [Milahin, 2016](#) ; [Wetter, 2016](#) ) material properties ( [Khadem et al., 2017](#) ) and fracture mechanics ( [Ciavarella et al., 1999](#) )—to mention only some.

Clearly, there are many complex tribology problems which have been solved, as e. g., those connected with hydrodynamic and elastohydrodynamic lubrication. It should also be noted that many tribological problems have been met with working practical solutions—otherwise we would not have functioning cars, trains, airplanes, and other modern conveniences.

Nonetheless, many such solutions were arrived at mostly by trial and error, in combination with iterative improvement. Many fundamental problems, particularly those involving dry and boundary lubrication remain not well understood.

## Is The Time Ripe for a “ Revolution” in Tribology?

Several developments of the last decades have the potential to change the future standing of tribology among other engineering sciences. Consider, for example, the theories of hydrodynamic and elastohydrodynamic lubrication ( [Hamrock and Dowson, 1981](#) ), understanding of hard coatings ( [Donnet and Erdemir, 2008](#) ) and lubrication additives ( [Spikes, 2004](#) ).

In the following I would like to discuss in more detail two key developments that concern contact mechanics.

### **FFT-Based Boundary Element Method: Searching for Consensus and New Paradigms in Tribology**

The first of these developments is an extremely effective numerical simulation method of contact of rough surfaces. It is known as the Fast Fourier Transform-based Boundary Element Method, or FFT-BEM. Following years of debate on the underlying theory, the engineering community created a tool that allows direct calculation of realistic contact conditions. Several modifications of this method are mentioned in [Müser et al. \(2017\)](#). The most common version of the FFT-Based Boundary Element Method ( [Putignano et al., 2012](#) ) can be applied both to normal and tangential contacts with arbitrary contact interaction ( [Pohrt and Li, 2014](#) ), to viscoelastic bodies ( [Carbone and Putignano, 2013](#) ; [Kusche, 2016](#) ) and adhesive ( [Popov et al., 2017](#) ; [Rey et al., 2017](#) ) contacts. This method recently became the standard method of numerical simulation of tribological contacts both in academic and industrial research and development and changed significantly the ways of thinking and the direction of further development of tribology. While around 2010 high resolution simulations of

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contact of rough surfaces were available to only a few leading groups worldwide, now they can be carried out in practically every tribological group, the corresponding programs are even provided for on-line simulations (Tribology [Simulator, 2018](#)).

### **Progress in Didactics of Contact Mechanics Since Hertz**

The second development is more of didactical nature. It does not contribute much to the results obtained in 136 years since the seminal work of Hertz ( [1882](#) ) but merely presents them in a form accessible even to undergraduate students. This didactic invention is the Method of Dimensionality Reduction (MDR) ( [Popov and Heß, 2015](#) ) which can be considered a reformulation of the solution method for contact of axi-symmetrical bodies first developed by Schubert ( [1942](#) ). In the literature, Schubert's method is mostly associated with the name of Sneddon, due to the Sneddon's highly cited paper ( [Sneddon, 1965](#) ). In reality, the method was suggested not only by Schubert but (later) also by [Green and Zerna \(1954\)](#) , Collins ( [1959](#) ), and Galin ( [1961](#) ) but it took decades until it became well-known and “ established” and Sneddon indeed did much for advertising this solution, including the translation and publication of the book of Galin.

The MDR, according to Barber ( [2018](#) ), is basically a reinterpretation of the equations of Schubert-Galin-Sneddon using a simple contact with a one-dimensional elastic foundation. MDR summarizes the known solutions and presents them in a simply reproducible mnemonic form. The true added value of the MDR becomes visible only when considering more general problems. Due to theorems allowing for (exact or approximate) reduction of tangential contact problems ( [Cattaneo, 1938](#) ; [Mindlin, 1949](#) ; [Jäger, 1995](#) ; <https://assignbuster.com/is-tribology-approaching-its-golden-age-grand-challenges-in-engineering-education-and-tribological-research/>

[Ciavarella, 1998](#)), viscoelastic contact problems ([Radok, 1957](#)) and adhesive contact problems ([Johnson et al., 1971](#)) to non-adhesive normal contact, the MDR becomes a very compact, universal and intuitive tool for understanding and analyzing a great variety of contact problems. As a matter of fact, it provides a sort of “pocket edition” of all solutions in contact mechanics of point contacts obtained by researchers in the last 136 years. This didactic tool requires only the basics of analysis for its application and thus makes contact mechanics available to a broad engineering community. Barber notes that MDR is comparable with the moment-area method for the solution of beam deflection problems in the mechanics of materials. Both have restricted fields of applicability—but wide enough to be worth studying by engineers; both are simple and instructive. All major problems of the mechanics of connections—such as normal and tangential contact, stresses at the surface and inside the material, viscoelastic contacts, adhesion, wear and fretting, influence of shape, and material gradients ([Heß, 2016](#)) on adhesive strength and wear as well as damping in oscillating contacts—this complete spectrum of essential contact problems can be analyzed with MDR without using complicated mathematical tools. However, integrating contact mechanics in the basic engineering courses remains a great challenge.

### **A Grand Challenge in Research of Friction: “Third Body”**

Surfaces have essentially different properties compared with the bulk of materials, and tribological loading massively changes the properties of surface layers. The interface properties of tribological contacts may be influenced by the composition of the atmosphere, humidity, presence of lubricants, adsorbed layers, and wear debris. The intermediate space of and



around the interface essentially determines the tribological properties and is called “third body” ( [Godet, 1990](#) ). To exaggerate somewhat, understanding friction means understanding the third body. The influence of the third body in a broad sense has been demonstrated on all scales. Thus, one of the great discoveries of nanotribology was structural superlubricity in the contact of well-prepared atomically smooth surfaces ( [Dienwiebel et al., 2004](#) ). However, the presence of flakes of lamellar solids that can freely rotate completely destroys the effect of superlubricity ( [Filippov et al., 2008](#) ). A similar effect can be due also to other impurities in the interface, even of single atoms ( [Müser et al., 2001](#) ). Under other conditions, interfacial processes are needed to achieve the state of low friction ( [Li et al., 2011](#) ). Intermixing and surface modification are also essential in classical macroscopic tribology, such as in combustion engines, where the formation of a chemically modified surface layer was shown to be the key for understanding tribological properties ( [Scherge et al., 2003](#) ). Even in systems with hard coatings, where, at the first glance, the essential role should be played by material properties, in reality it is the surface modification of these properties which does matter ( [Pastewka et al., 2010](#) ). The same is valid on the mesoscale: surface changes lead to time dependent kinetics of tribological properties ( [Ostermeyer, 2003](#) ). Contact mechanics of rough surfaces made enormous progress in recent years, but its necessary input, the surface topography, doesn't remain static in the course of a tribological process. Thus, one of the most valuable and effective modern tools of looking into the interface—the FFT-based BEM helps understanding the *given* configuration of the surfaces but does not help understanding its

*changes* as it cannot describe inelastic behavior and is not capable of describing such highly non-linear processes as formation of wear debris and material intermixing. Finding new concepts for characterizing and understanding the third body is therefore an urgent need of tribology and one of its great challenges.

We hope that now is the right time to approach this “ problem of the third body.” On the empirical level it could be a combination of non-equilibrium thermodynamics of surface layers, similar to the framework used in [Bryant et al. \(2008\)](#) and kinetics of formation and wear of the surface layers similar to the works of [Ostermeyer and Müller \(2006\)](#). For example, it is generally recognized that in lubricated contacts the wear process is controlled by formation and wearing out of the boundary lubrication layer build through mechanochemical reactions of additives with the surfaces. The wear process of this boundary layer could be described in the general framework suggested in 1958 by Rabinowicz ( [1995](#) ) and confirmed by direct quasi-molecular simulations in [Aghababaei et al. \(2016\)](#). This concept is a generic and robust approach as it basically says that the wear particles can appear if the stored elastic energy is sufficient for their formation. The process of wear particle initiation has to be completed by mechanics of wear debris in the gap between two bodies and the transport of wear particles. The latter could be described using a macroscopic empirical framework similar to Schargott ( [2009](#) ). The reverse process of the layer *deposition* can be described using the classical concept of mechanically activated thermal processes ( [Spikes, 2018](#) ) which was validated experimentally also for the particular process of additive deposition ( [Gosvami et al., 2015](#) ). Detailed discussion of the

current state of tribology and its topical problems can be found in a collaborative analysis ( [Vakis et al., 2018](#) ). The above suggestions are of course only my personal attempt to predict the future development of understanding of the third body.

## **Golden Age of Tribology**

Classical tribology covering such applications as ball bearings, gear drives, clutches, brakes, etc. was developed in the context of mechanical engineering. But now contact mechanics and tribology expand to qualitatively new fields of applications, which are at the forefront of the global development trends of technology and society, in particular micro- and nanotechnology ( [Bhushan, 2017](#) ) as well as biology ( [Gorb, 2009](#) ) and medicine ( [Willert et al., 2005](#) ; [Paterson, 2007](#) ; [Li et al., 2008](#) ). At the same time, tribology developed experimental methods, theoretical concepts, and numerical tools allowing effectively mastering the seemingly complicated physics and mechanics of interconnections. After intensive and controversial discussions, recently, several attempts have been undertaken to achieve consensus on the present state and available tools of tribology ( [Müser et al., 2017](#) ; [Vakis et al., 2018](#) ). These attempts and the rapid expansion into new research areas such as nano-technology and life sciences give hope that the coming years will be a true golden age of tribology.

## **Author Contributions**

The author confirms being the sole contributor of this work and has approved it for publication.

## Conflict of Interest Statement

The author declares that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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