

Processes states: a  
cpu (central  
processing unit)



**ASSIGN  
BUSTER**

Processes in a system cycle between two states: a CPU (Central Processing Unit) burst, in which calculations are carried out, and an I/O (input/output) burst, in which data is either sent to or received by the system. The Central Processing Unit (CPU) attempts to maximise the efficiency and 'fairness' of a CPU, by allowing a process to utilise the CPU, whilst another waits for an I/O. If this isn't addressed, CPU cycles are lost whilst the CPU waits for a single process's I/O. The role of the CPU scheduler is to find the subsequent process for an inactive CPU, from a queue of immediately available processes. The order in which the processes are handled depends on the algorithm implemented by the CPU scheduler.

There are two types of algorithms applied: non-preemptive and preemptive. Non-preemptive algorithms must be applied when a new process is required, i. e. when either a process is terminated, or when a process transitions from a running to waiting state. However, when a process goes from either a running state to ready state, or from waiting state to ready state, preemptive algorithms are optimum. In order to ensure that preemptive algorithms can be implemented, it must be ensured that the hardware can support time interrupts. Once the scheduling algorithm has selected a process, the dispatcher hands control of the CPU to it.

This involves a context switch, a user mode switch and then a jump to the correct location in the newly loaded program. The time taken for this to complete is called the dispatch latency. When attempting to choose the optimum algorithm to implement in CPU scheduling, there are criteria to adhere by in order to make the best decision: CPU utilisation should be maximised, in order not to waste a single CPU cycle wherever possible, and the '

throughput' (number of processes executed per unit time) should also be maximised. However, the turnaround time, waiting time and response time should all be minimised as much as possible. <http://www.studytonight.com/operating-system/cpu-scheduling>

For the following evaluation of algorithms, a single CPU burst is assumed per process. First-Come First Served (FCFS) is the most primitive form of scheduling, involving a first-in, first-out basis for the queue order, and is a non-preemptive algorithm. The benefits of using FCFS is that it is simple in application and allows the process being executed to complete its CPU burst. Therefore, there is no need to context switch and take CPU away from process preemptively. However, as well as having long waiting times, FCFS can also slow the system down in a process known as the convoy effect; preventing the CPU from being optimally used as after the large process finished, the CPU goes through periods of high intensity processing (with a minimal I/O) and vice versa 3.

RoundRobin (RR) shares similarities with FCFS, however, the CPU bursts are given limits called time quantum. If the process completes before the time quantum limit runs out, the schedule continues in a first in, first out manner. However, if the quantum timer limit expires, the time interrupt occurs and the process is placed at the back of the queue (the algorithm is preemptive). This is ideal for small tasks, as even if a large process is placed higher in the queue than a short one, each get a 'fair' attempt.

However, this proves problematic with processes of equal time, where FCFS could have a lower throughput and the overhead produced through 'context

switching' reduces the CPU utilisation 3. Shortest-Job-FirstScheduling (SJF) arranges the queue in ascending order of length of CPU bursttime.