

Pre lab springs

[Science](#), [Physics](#)



Springs and Oscillators From the theory section of the lab we have two ways to determine the angular frequency ω of oscillations of the mass m : $\omega = 2\pi/T$ and $\omega = \sqrt{k_d/m+m_0}$

a. Both ways to determine angular frequency ω must give the same value.

Equate the above equations and solve for T^2 .

$$\omega = \sqrt{k_d/m+m_0}$$

k_d is the spring constant between the initial stretch and the final stretch ($x - x_0$)

k varies with the level of stretch of the spring, thus, $k_d = \delta F / \delta x$

$$F = mg$$

$$200g * 9.8$$

$$0.2 * 9.8 = 1.96N$$

Let the stretch be from 0 cm to 10 cm making the stretch, $x = 10\text{cm} = 0.1\text{m}$

$$k_d = 1.96N / 0.1\text{m}$$

$$= 19.6N/m$$

Considering the range of masses from 200g to 600g, $m+m_0 = 200+600$

$$800g = 0.8\text{kg}$$

$$\text{Thus, } k_d/m+m_0 = 19.6/0.8 = 24.5$$

$$\omega = \sqrt{24.5} = 4.95$$

$$\omega = 2\pi/T$$

$$\text{But } \omega = 4.95, \text{ thus, } 4.95 = 2\pi/T$$

$$4.95T = 2\pi$$

$$T = (2 * 3.142) / 4.95$$

$$T = 1.269$$

$$T^2 = 1.61$$

The result in part (a) should look like the standard equation for a straight line, $y = mx + b$, if the variable for the x-axis is taken to be the mass m . This means if we plot T^2 vs. m we would see a straight line.

b. Compare the standard form of the equation for a straight line and the result for part (a) and determine the theoretical value for the slope in terms of constants and the dynamical spring constant k_d . In terms of the slope (and other constants), what is the value of the dynamical spring constant k_d ?

From the above calculation, $T^2 = K_d / m + m_0$

Meaning that $T^2 (m + m_0) = K_d$

When rearranged,

$$T^2 = K_d m + m_0$$

The standard equation of a straight line is $y = mx + c$. The theoretical y-intercept in the standards equation of a straight line compares (corresponds) to the determined value of T^2 . The slope (constant) is normally represented by the value of m in the standards equation of a straight line and in this case corresponds to K_d .

The dynamical spring constant (K_d) is the spring constant between the initial stretch and the final stretch ($x - x_0$)

K varies with the level of stretch of the spring, thus, $K_d = \delta F / \delta x$

$$F = mg$$

$$200g * 9.8$$

$$0.2 * 9.8 = 1.96N$$

Let the stretch be from 0 cm to 10 cm making the stretch, $x = 10\text{cm} = 0.1\text{m}$

$$K_d = 1.96N / 0.1\text{m}$$

$$= 19.6 \text{ N/m}$$

c. Again, compare the standard form of the equation for a straight line and the result for part (a), what should the theoretical value for the y-intercept be in terms of constants and the dynamical spring constant k_d and m_0 the effective mass of the spring? In terms of the y-intercept (and other known values), what is the value of the effective mass of the spring m_0 ?

As argued above, the standard equation of a straight line is $y = mx + c$. This equation implies that y is the same as c since it is the value where the line cuts the y-axis. C is the intercept on the y-axis.

In comparison, if T^2 compares to y , and $T^2 = 1.61$, then it means that the straight line of the graph of T^2 against m cuts the x-axis at 1.61. This value depends on the constant K_d , since the spring constant results from the resultant forces applied on the spring, the restoring force and the mass, m_0 applied on the spring.

The effective mass, m_0 , corresponds to c , such that in order to determine the value of the effective mass, the value 2.418 is very important.

The spring equation, $T = 2\pi\sqrt{(m_0/K_d)}$, implies that $m_0 = (K_d T^2)/(4\pi^2)$

$$(19.6 * 1.61)/(4 * 9.872) = 0.8 \text{ kg}$$