

Control control limit (lcl) represent the boundaries of

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Control charts are widely used tools of statistical quality control in industrial environments since its inception by Shewart in 1920's. The major function of control charting is to detect the occurrences of assignable causes so that the necessary corrective action may be taken before large quantity of non conforming product is manufactured. A survey conducted by Saniga and Shirland (1977) shows that on continuous measurement scale the control chart for averages dominates the use of any other control chart technique. All control charts have a common structure. A plot of the result of repeated sampling is made on a vertical scale against the number of samples plotted horizontally.

The center line of the chart represents a long term average of the process statistic or its standard value. The upper control limit (UCL) and Lower control limit (LCL) represent the boundaries of typical statistic variation. The process call for adjustment if the points fall outside the control limits.

Departures from expected process behavior within the limits (non random patterns on the chart) can be detected by using different run tests for pattern recognition (Nelson (1985)). On using control charts two kinds of errors may occur: over adjustment and under adjustment. Uncertainty of inferences based on sampling statistic is the major cause for these errors.

The magnitude of the errors depends on the decision-making method. It is beneficial that a control chart detect process change quickly so that the causes of any undesirable changes can be identified and removed. It is also beneficial that the rate of false alarms generated by the control chart be low in order to maintain the confidence of process operations in the chart.

Sampling cost will be an issue for most of the applications, thus it is important that a control chart be able to provide fast detection of process change and a low false alarm rate with a reasonable rate of sampling. So the statistical performance of a control chart is often evaluated by considering, for a given false alarm rate and sampling rate, the expected time required by the chart to detect various process changes. It has been found in recent years that the statistical performance of control charts can be improved considerably by changing the rate of sampling as a function of the data coming from the process. The basic idea is that whenever there is an indication of a problem with the process the sampling should be more intensive and less intensive when there is no indication of a problem. There are many ways in which the sampling rate can be varied as a function of process data.

One of the ways is to vary the sampling interval: a short sampling interval is used when there is an indication of a problem and a long sampling interval is used when there is no indication of a problem. The resulting variable Sampling interval (VSI) control charts have been studied broadly (see, e. g., Reynolds et al (1988) ; Zee (1990), Runger and Pignatiello (1991); Baxley (1996); and Reynolds (1996a, 1996b)).